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APACHE 6

MULTIBEAM
MARINE DRONE



MARINE SURVEY & CONSTRUCTION



ADVANCED USV WITH NORBIT MULTIBEAM ECHOSOUNDER

The APACHE6 USV is an innovative, fully integrated solution for 3D bathymetric surveys, positioning of underwater objects, offshore construction, underwater archaeology and wreck salvage. Built around a triple-hull vessel and optimized for the Norbit™ multibeam echo sounder series, the APACHE 6 offers a fully autonomous survey mode, powered by field-proven CHCNAV absolute straight line technology, to follow a predetermined path even in adverse current conditions.

The APACHE6 multibeam echosounder USV reduces survey time, improves work efficiency and produces high-resolution data to always meet the requirements of the most demanding marine survey projects.

OPTIMIZED FOR NORBIT MULTIBEAM ECHOSOUNDERS

High-end turnkey multibeam USV solution for high resolution bathymetry.

APACHE 6 design is optimized for the NORBIT iWBMSe, iWBMS and iWBMSh-STX series offering with high end performances to match the most demanding hydrographic survey requirements.

LIGHTWEIGHT FOR EASY DEPLOYMENT

Allow two operators to cope with most of remote deployment conditions.

Made of macromolecule polyester carbon fiber and Kevlar fiber-glass weighting 15 kg without sensors.

HIGH PERFORMANCE TRIPLE-HULLED VESSEL DESIGN

Versatile USV solution for offshore, coastal and inland water and lakes surveys.

Its dual detachable floating bodies keep the hull balanced even in the rapid current situation. Removing the floating bodies allows operation in shoals, channels and shallow rivers without run aground.

OPTIONAL TERRESTRIAL MAPPING LASER SENSOR

Collect up to 300 000 points per second at a 30 x 360-degree coverage.

The optional NORBIT iLiDAR mapping sensor provides high accuracy combined marine and terrestrial 3D survey in a single pass saving significant processing time when performing harbor and river surveys with height clearance evaluation (transmission lines, bridges...).

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FOR HIGH RESOLUTION BATHYNETRIC PROJECT

SPECIFICATIONS

| Physical | | | |
|-----------------------------|------------------------------------|--|--|
| Size (L x W x H) | 1.8 m x 0.55 m x 0.25 m | | |
| Weight (no instrument) | 15 kg | | |
| Weight (Typical instrument) | 40 kg | | |
| Hull Material | Carbon Fiber | | |
| Hardware | Anodized Aluminum, Stainless Steel | | |
| Typical Survey Speed | 2-2.5 m/s | | |
| Maximum Speed | 3.5 m/s | | |
| Draft | 0.18 m | | |
| Payload (typical) | 60 kg | | |
| Communications | | | |
| Communication Way | UHF and network bridge | | |
| Network bridge Frequency | 900 MHz / 5.0 GHz | | |
| Communication Distance | 1.5 km / 0.8 km | | |
| Communication Port | RS232 / Internet access | | |
| R/C Control | Hitec with Vessel Telemetry | | |
| R/C Antenna | Omini Directional | | |
| R/C Range | Up to 1 km | | |
| R/C Frequency | 2.4 GHz | | |

| iLiDARLaser S | ensor (Integration Option) | | | |
|---|--|--|--|--|
| Frame Rate | 5-20 Hz (10 Hz default) | | | |
| Wave Length Peak | 905 nm | | | |
| Output | Up To 300.000 Points Per Sec | | | |
| Accuracy | 2 cm | | | |
| Field Of View | 30° vertical, 360° horizontal | | | |
| Range | 100 m | | | |
| Power | 8 W | | | |
| Electrical | | | | |
| | Electrical | | | |
| Power | Electrical 4 x 18.5v 40Ah battery Lipo / 2 x 18.5v 15Ah battery Lipo | | | |
| Power Motor | 4 x 18.5v 40Ah battery Lipo / | | | |
| | 4 x 18.5v 40Ah battery Lipo / 2 x 18.5v 15Ah battery Lipo | | | |
| Motor | 4 x 18.5v 40Ah battery Lipo / 2 x 18.5v 15Ah battery Lipo 2 x Brushless Thruster | | | |
| Motor Navigation Mode Battery Endurance (1) | 4 x 18.5v 40Ah battery Lipo / 2 x 18.5v 15Ah battery Lipo 2 x Brushless Thruster Automatic / Manual 2-3 h (operating time can be | | | |

USV calibration, real-time USV tracking and checking the status of USV operation.

*Specifications are subject to change without notice.

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NORBIT MBES Specifications

Norbit IWBMSe Norbit IWBMS (Standard) NORBIT IWBMSh-STX Туре







| | The state of the s | | | | |
|--------------------------|--|--|---|--|--|
| Swath Coverage | 5-210° | 7-210° | 5-210° | | |
| Range Resolution | | | | | |
| Number Of Beams | 256-512 | | | | |
| Operating Frequency | 400 KHz | | | | |
| Depth Range | 0.2 - 275 m | | | | |
| Ping Rate | Up to 60 Hz, Adaptive | | | | |
| Resolution : Standard | 0.9° x 1.9°@400 kHz And 0.5° x 1.0°@700 kHz . Narrow Option 0.9° x 0.9°@400 kHz And 0.5° x 0.5°@700 kHz. | | 0.9° X 0.9°@400 kHz or 0.5°X 0.5°@700 kHz | | |
| Position | HOR: ±(8mm+1ppm X DISTANCE FROM RTK STATION) VER: ±(15mm+1ppm X DISTANCE FROM RTK STATION | | | | |
| Heading Accuracy | 0.08° | 0.03° | 0.02° | | |
| Pitch /Roll Accuracy | 0.03° | 0.02° | 0.01° | | |
| Heave Accuracy | 5 cm | | | | |
| Weight | 6.5kg (AIR) 2.4kg (WATER) | APPROX 9.5kg (AIR) LESSTHAN 6kg (WATER) | APPROX 11 kg (AIR) LESSTHAN 6.5 kg (WATER) | | |
| Interface | ETHERNET | | | | |
| Power Consumption | 60 W | | 70 W | | |
| Operating Temp | -20°C to + 60°C | | | | |
| | | *************************************** | | | |

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